	Quality and Innovation
	Teaching Pendant SEL-T, TD, TG
	First Step Guide Fifth Edition
	Thank you for purchasing our product. Make sure to read the Safety Guide and detailed Instruction Manual as well as this First Step Guide to ensure correct use. This Instruction Manual is original.
	Warning : Read the instruction manual carefully and follow the instruction manual when handling this equipment. Please downloaded the user's manual from our website. You can download it free of change. User registration is required for first time users. URL:www.iai-robot.co.jp/data_dl/CAD_MANUAL/ Keep a printout of the introduction manual near the equipment in which this product is installed so that it can be checked at all times, or display it on your computer, tablet terminal, etc. so that you can check it immediately. If you need a bound copy of the instruction manual, order it from the nearest sales office listed in the First Step Guide or at the end of the instruction manual. It will be provided for a fee.
	 Using or copying all or part of this Instruction Manual without permission is prohibited. The company names, names of products and trademarks of each company shown in the sentences are registered trademarks.

Product Check

This product is comprised of the following parts if it is of standard configuration. If you find any fault in the contained model or any missing parts, contact us or our distributor.

1. Parts	(The option is excluded.)	

No.	Part Name	Model	Reference		
1	Main Body	Refer to "How to read the model plate", "How to read the model"			
Accessor	Accessories				
2	First Step Guide	ME0280			
3	Safety Guide	M0194			

2. Instruction Manuals related to this product

No.	Name	Manual No.
1	Teaching Pendant SEL-T/TD/TG Instruction Manual	ME0183
2	XSEL-J/K Controller Instruction Manual	ME0116
3	XSEL-JX/KX Controller Instruction Manual	ME0119
4	XSEL-P/Q/PCT/QCT Controller Instruction Manual	ME0148
5	XSEL-PX/QX Controller Instruction Manual	ME0154
6	XSEL-R/S/RX/SX/RXD/SXD Controller Instruction Manual	ME0313
7	Table Top Type Robot TT Instruction Manual	ME0149
8	Table Top Type Robot TTA Instruction Manual	ME0320
9	SSEL Controller Instruction Manual	ME0157
10	ASEL Controller Instruction Manual	ME0165
11	PSEL Controller Instruction Manual	ME0172

3. How to read the model plate

Model ———	MODEL	SEL-T		
Serial number	SERIAL No	. 900109942	A1	MADE IN JAPAN

4. How to read the model

S	Ε	L	-	Т	- J	

<madal></madal>	
For XSEL Co	ontroller, and TT
SEL-T	: Standard type
SEL-TD	: Deadman switch equipped type
SEL-TG-25	: Safety category 4 compliance type
For ASEL, P	SEL and SSEL Controller
SEL-T-J	: Standard type,
	with connector converter cable
SEL-T-JS	: Standard type,
	with connector converter cable
SEL-TD-J	: Deadman switch equipped type

SEL-TD-J	: Deadman switch equipped type
	with connector converter cable
SEL-TD-JS	: Deadman switch equipped type
	with connector converter cable
SEL-TG-26H	: Safety category 4 compliance type

Support Models

upport Models
Support Started Version
V1.00
V1.12
V1.12
V1.12
V1.16

Basic Specifications

Item	Specification
Compliance with UL and CE Standards	Compliant
Surrounding Air Temperature & Humidity	Temperature : 0 to 40°C Humidity : 10 to 90% (non-condensing)
Protection Code	IP54 (Excluding cable connectors)
Surrounding Environment	No corrosive gas
Weight	Approx. 0.4kg (Excluding cables)
Cable Length	5m

External Dimensions



Connection Diagram

[SEL-T]

Connect to the teaching connector. Shown below is a connection to XSEL-P type for an example.



[Connection of the SEL-TG and IA-LB-TG]



Γ	\triangle	Note :	When the tea
			plug DP-4 Int





This shows an example of the ASEL Controller.

6		
	Â	Note : When the te
		plug DP-4S

[Connection of the SEL-TG and IA-LB-TGS]

XSEL Controller	



Â	Note : When the te		2
		plug DP-4S i	İ

aching pendant SEL-TG is not to be connected, make sure to insert the dummy to the adaptor for the teaching pendant.

[Connection of the SEL-TD and IA-LB-TGS]



aching pendant SEL-TG is not to be connected, make sure to insert the dummy into the adaptor for the teaching pendant.

Operation Panel



- 1) LCD Screen
- 2) EMERGENCY STOP (Emergency Stop Push Button Switch) Executes emergency stop
- 3) LED
- JOG

When this LED is lit, jog operation is possible with 1-, 2-, 3-, 4-, ALL-, 1+, 2+, 3+, 4+ or ALL+

MOVE

When this LED is lit, position movement or continuous movement operation is possible with 1-2-, 3-, 4-, ALL-, 1+, 2+, 3+, 4+ or ALL+.

SERVO

When this LED is lit, servo ON/OFF operation is possible with 1-, 2-, 3-, 4-, ALL-, 1+, 2+, 3+, 4+ or ALL+.

HOME

When this LED is lit, homing operation is possible with 1-, 2-, 3-, 4-, ALL-, 1+, 2+, 3+, 4+ or ALL+.

4) F1 F2 F3 F4 keys (Function keys)

Correspond to each item in the LCD Screen (function key section). The LED is lit when the relevant key is operable.



5) SF key (Shift key)

f there are more than 5 selectable functions (" \rightarrow " will be displayed at right side of the function key area), it will change the display items in the function key area. When the key is operable, its LED is lit.

6) WRT key (Write key)

Transmits edit data to the controller. (Data will be saved in the memory of the controller.) Only the data shows on the LCD Screen will be transmitted. (Plural Position No., Program Step No., etc., can't be transmitted all together at the same time.)

7) ESC key (Escape key)

Returns to the previous status from the current status. If you press this key during data input, the data will be cancelled

8) BS key (Backspace key) If you press this key during data input, clear one letter before. At other time, clear the data where the cursor is placed.

9) < (Cursor key) loves the curso

10) Numeral keys

You can input numeric, alphabet, and sign.

When the cursor is at any item requiring the input of characters other than "0" to "9" (such as hexadecimal and character strings), the input mode selection is displayed in the function key area (Alph: alphabet symbol input Num: numerical value input)

11) 🖾 key (Return key)

Confirms the input data and moves the cursor position forward.

Increment or decrement edit and display item No. (Position No., Program No., Step No., etc.) 13) MOVE key

Enables actuator movement or continuous operation. The LED of MOVE is lit.

(It is valid in the Teac (teach) mode area.) When you press a jog key such as 1+ and 1- after enabling movement or continuous operation, movement action starts. However, it is required to switch servo ON when the servo is OFF. Jog operation is made possible after the action has been completed or stopped. The LED of JOG is lit

14) STOP key

Stops actuator movement or continuous movement. (It is valid in the Teac (teach) mode area with the servo ON.)

15) SERVO key

Enables axis servo ON/OFF switching operation. The LED of SERVO is lit up.

(It is valid in the Teac (teach) mode area.) When you press a + jog key such as 1+ after enabling servo ON/OFF switching operation, the servo is turned ON. When you press a – jog key such as 1-, the servo is turned OFF. Jog operation is made possible after the servo has been turned ON/OFF. The LED of JOG is lit. However, when the servo is OFF, the actuator cannot be moved by jog or inching operation unless the

servo is turned ON 16) HOME key

Enables homing operation. The LED of HOME is lit. (It is valid in the Teac (teach) mode area.) When you press a jog key such as 1+ and 1- after enabling homing operation, homing starts. However, it is required to turn the servo ON when the servo is OFF Jog operation is made possible after homing has been completed. The LED of JOG is lit.

- 17) 1- 1+ 2- 2+ 3- 3+ 4- 4+ ALL- and ALL+ (Jog keys)
 - 1- Negative direction jog movement for the 1st axis and 5th axis 1+ Positive direction jog movement for the 1st axis and 5th axis 2– Negative direction jog movement for the 2nd axis and 6th axis
- 2+ 3-Positive direction log movement for the 2nd axis and 6th axis Negative direction jog movement for the 3rd axis
- (It is valid in the Teac (teach) 3+ Positive direction log movement for the 3rd axis mode area with the servo ON) 4– Negative direction jog movement for the 4th axis 4+ Positive direction jog movement for the 4th axis
- ALL- Negative direction jog movement for all axes ALL+ Positive direction jog movement for all axes
- Such jog actions with the JOG button are also valid for any not-homed axes. However, coordinate values in this case have no meaning. Therefore, be extremely careful about interference with the stroke end
- If jog operation is performed to the axis in action under the operation-button-acceptable condition, the operation of the applicable axis is aborted when the JOG operation button is turned OFF. (The next operation starts, if any.)
- 18) Deadman Switch *Option
- There are three stages for the dead-man switch. The ON/OFF in each stage are described as follows. The condition where finger is released from the switch, or the force of
- Switch OFF 1st Stage pressing the switch is very weak. 2nd Stage Switch ON Condition where the switch is pressed with appropriate force. 3rd Stage Switch OFF Condition where the switch is pressed strongly.

The servo-motor can be turned ON under the switch ON condition.

When the switch is turned OFF, the driving power source is disconnected and the servo-motor is turned

- Even when the switch is turned OFF, the operations in the modes where turning ON the servo-motor is not required are available (such as edit mode)
- Some controllers such as the X-SEL-K controller display the message shown below when the power is turned ON. If you press the ESC key, the mode selection screen will be displayed and operation will become
- possible in the mode not requiring servo ON even in the switch OFF condition



• When the switch is OFF, the panel window 7-segment LED of the X-SEL-K or KX controller displays 'def'

The panel window 7-segment LED of the X-SEL-P/Q, PX/QX controller or TTA displays 'enb'

- The Deadman switch is valid when the controller's mode switch is on the MANU side
- The driver power cannot be cut off regardless of the switch condition when the controller's mode switch is on the AUTO side

details how to create a program.

1) Command (Cmnd) 3) Operation 2

1) Command (Cmnd)

4) Output (Pst)

6) Input Condition (N•Cnd)

It is required to set the the position table.
The items to set differ of controller for the details

F
Position No.
1
2
3
4
5
6

Positioning Position fo 1st Axis



for 1st Axis



Program Table Input Window



- PATH Operation for instance, it is to input the start Position No.. 3) Operation 2 (Operand 2) : It is to input details of Operation 1 related to commands and declarations. For
 - PATH Operation for instance, it is to input the completion Position No... : It is to input the output port and input port to output the operation completion result after the command is executed.
- 5) Expansion Condition (E) : It is used to join multiple input terms with "AND" or "OR".
 - : If a negative condition is desired for the input term, put N.
 - If the command is to be executed with the conditions of I/O or the flag, put the I/O or flag

Position Table Input Window

position (coordinate values), velocity, acceleration and deceleration to

depending on the model. Refer to the Instruction Manual of the used





for 2nd Axis

[Window to Input Velocity, Acceleration and Deceleration]

Vel Canc Axis

Deceleration

Operation

After the power is supplied to the controller, a window shown below will be displayed. An operation can be performed on the operation panel. [Refer to the operation panel]

Select a menu and execute.

Edit (F1 key) : To perform teaching operation to edit program table, position table, etc.
 Play (F2 key) : To drive program.

• Moni (F3 key): To monitor input and output ports, error list, etc.

Ctl (F4 key) : To control software reset, absolute reset, safety speed valid/invalid, etc.

The operation window is constructed with a few layers and a selected menu shows some related operation windows.

[Refer to Teaching Pendant SEL-T/TD/TG Instruction Manual for details.]

How to Operate (Examples)

Data Input to Position Table

The chart below shows how to set 0mm to Position No.0 on the 1st axis and 50mm to the position on the 2nd axis when 2 axes are connected for example.

No.	Operation	Screen	Reference
1	Press F1 key (Edit).	Mode Selection	
		(Édit) Play Moni Ctl	
2	Press F1 key (Posi).	Edit (Posi) Prog Sym Para	
2			
3	Press FT key (Mdl).	Midi) Teac Copy Clr	
4	Input a number "0" and press		"x xxx" will be displayed when
	the return key. The display shows "0.000", and the axis number changes to "2" and the cursor position moves to the	Midii - 1 Axis 2/2 0.000 ×.××× Vel Canc Axis	the position data is not registered.
	position data for the 2 nd axis.		
5	Input "50" to the 2 nd axis position data and press the return key.	Midi – 1 Axis 1/2 0.000 50.000 Vel Canc Axis	The cursor position moves each time the return key is pressed. When you made a typing error, put the cursor to the position where you would like to correct and rewrite. It is also available to change the input data back to "x.xxx" with the (Canc) key.
6	Press WRT key to transfer the data. The Position No. gets forwarded to "2".	Position No.2 // Mdi - (2) Axis 1/2 x.xxx Vel Gang Axis	
7	Broos ESC key to may a the	Hdi = 2 A x i e 1 - 2/2	
,	cursor back to the Position No	CIr Axis	
8	Press ESC key again to return to Edit Mode.	Edit-Posi Ndi Teac Copy Clr	
9	Press ESC key once again	E d i t	
5	to go to the flash ROM writing window.	Posi Prog Sym Para	
10	Press F1 (Yes) key if you desire to write the data to the flash ROM.	Flish Flish Write ? Yes No	Press F2 (No) key if you do not desire a writing.
11	'Please wait' blinks while in	Fish	* Do not turn off the controller
	the flash ROM writing process.	Writing Flash ROM Please Wait	during this process.
12	Return to the edit window by pressing ESC key.	Flsh Complete!	
13		Edit	
		Posi Prog Sym Para	

Data Input to Program Table

The chart below shows how to input 'HOME 11' to Program No.0 for example.

No.	Operation	Screen	Reference
1	Press F1 key (Edit).	Node Selection	
2	Press F1 key (Prog).	Edit Posi Prog Sym Para	
3	Press F1 key (Mdfy).	E d i t - P r o g	
4	The display switches to the Program No. input mode window. You will be able to see the cursor on the Program No Press the return key to move the cursor to the Step No	Program No. Step No.	If program data is already input, you should either overwrite (the original data will be erased) the data or select another Program No. with no data being written. The Program No. or the Step No. which the cursor is on can be changed with the data of the keys. Also, the Program No. and the Step No. can be changed by an input of numeral keys and pressing the return key.
5	The cursor moves to the Step No	Pg 1 - <u>1</u> :	
6	 Press the return key. Input the command. The command is displayed in the function key line. How to Search Command 1) Press SF key when the cursor is on the command input line to show the commands in the function line in the alphabetical order. Press key to show them in the back order. 2) Alphabets are allocated to each numeral key. (e.g. For "9", G,H and I are allocated.) Press a numeral key when the cursor is on the command input line, and the first command that starts with an alphabet allocated to the pressed numeral key is displayed in the function key line. Display the command to input on the function line with the methods 1) and 2), and press the corresponding function key 	P & 1 - 1 : - - ABPG ACC ACHZ ADD - Command starting with "G" P & 1 - 1 : - EXPG EXSR FWID GACC- Command starting with "H" P & 1 - 1 : - EXPG EXSR FWID GACC- Command starting with "H" P & 1 - 1 : - EXPG EXSR FWID GACC- Command starting with "H" P & 1 - 1 : - EXPG EXSR FWID GACC- Command starting with "H" P & 1 - 1 : - EXPG EXSR FWID GACC- Command starting With "H" P & 1 - 1 : - EXPG EXSR FWID GACC- Command Starting With "H" P & 1 - 1 : - Command Starting With "H" P & 1 - 1 : - Command Starting With "H" P & 1 - 1 : - Command Starting Command Starting Starting Command Starting Command Starting Starting Command Starting Starting Command Starting Starting Command Starting Startin	
	How to Search HOME Command Press the 9 key to show a command start with either of G, H or I. (Some of the commands cannot be displayed only with the numeral keys. For those, combine the numeral key with SF key to display.) Show "HOME" on the function key line, and then press F4 (HOME) key. (Press BS key if desired to turn the command input line to blank.) Press the return key.	Pg 1- 1 : Howe Gvel Hold (Howe) IFEO-	
7	The cursor moves to Operation 1.	Pg 1 - 1 : H 0 M E _	
0	Input "11" and press the return key.	Sym *	
ð	the data key to the controller. The Step No. goes forward to 2.	rg i - 1 : HOME 11 - Sym *	
9	Press ESC key.	Step No.2	

NO.	Operatio
10	Press ESC key. (The cursor moves Program No)
11	Press ESC key. The display goes ba program edit window
12	Press ESC key. The display goes ba edit window.
13	Press ESC key.
14	Press F1 (Yes) H desire to write the d flash ROM.
15	'Please wait' blink the flash ROM writir
16	Now, it is completed flash ROM. Return to <u>the edi</u> t w
	pressing ESC ke
If the o	connection does n
	Description
Comr	munication connectio
"enb"	is displayed on the L
	Head Office: 577
	Hea
	Chicago
	Atlanta Offi
	IA
	Ober d
	Duttons Way, Shads
	1
SH	ANGHAI JIAHUA BU
	NO. 10 11 12 13 14 15 16 If the of Common set of the of

825 PhairoiKiiia Tower

n	Screen	Reference
to the	Pg 1 - 1 <u>2</u> : Ins Del Cmnt / 1	
ack to the w.	Pg 1-12: / 1	
ack to the	Edit-Prog Mdfy Copy Clr	
	Edit Posi Prog Sym Para	
key if you lata to the	Flsh Flash Write ? Yes No	Press F2 (No) key if you do not desire a writing.
ks while in ng process.	Flsh Writing Flash ROM Please Wait	* Do not turn off the controller during this process.
d to write the rindow by ey.	FIsh Complete!	

Troubleshooting

ot work properly, check the following item.		
	Measure	
on with the	Set the mode switch on the controller to "MANU" if it is on "AUTO" side.	
LED.	For XSEL-P and PX controllers, set the teaching pendant changeover switch to the "left side" if it is on the "right side".	



Quality and Innovation

IAI Corporation

7-1 Obane Shimizu-KU Shizuoka City Shizuoka 424-0103, Japan TEL +81-54-364-5105 FAX +81-54-364-2589 website: www.iai-robot.co.jp/

IAI America, Inc.

ad Office: 2690 W. 237th Street, Torrance, CA 90505 TEL (310) 891-6015 FAX (310) 891-0815 to Office: 110 East State Parkway, Schaumburg, IL 60173 TEL(847) 908-1400 FAX (847) 908-1399 ice: 1220 Kennestone Circle, Suite 108, Marietta, GA 30066 TEL (678) 354-9470 FAX (678) 354-9471 website: www.intelligentactuator.com

I Industrieroboter GmbH

der Röth 4, D-65824 Schwalbach am Taunus, Germany TEL 06196-88950 FAX 06196-889524 website: www.iai-automation.com

Technical Support available in Great Britain



sworth Business Park, Blackburn, Lancashire, BB1 2QR, United Kingdom TEL 01254-685900 website: www.lcautomation.com

AI (Shanghai) Co., Ltd.

JSINESS CENTER A8-303, 808, Hongqiao Rd. Shanghai 200030, China TEL 021-6448-4753 FAX 021-6448-3992 website: www.iai-robot.com

IAI Robot (Thailand) Co., Ltd.

825 PhairojKijja Tower 7th Floor, Debaratana RD., Bangna-Nuea, Bangna, Bangkok 10260, Thailand TEL +66-2-361-4458 FAX +66-2-361-4456 website:www.iai-robot.co.th

Manual No.: ME0280-5B