_	12A		
		3. How to Read Model Nameplate	
		Model number	1. Basic Specification
	Quality and Innovation	INITECT IN OUT IN ON THE INFORMATION IN OUT IN	Itom
	Touch Panel Teaching	Serial number Applicable Controllers	
	Dondont TD 02	ACON-C6/C6B/CYB/P0B/PLB X5EL-P/0/PX/0X/PCT/0CT PCON-C/06/CF/C7/2E/P0/PL X5EL-P/0/PX/0X/PCT/0CT PCON-CA/CF/C7/C7/2E/P0/PL X5EL-P/0/PX/0X/PCT/0CT	Power Supply Voltage Range
	Pendant IB-02	POIN-CFP/CGBP/CGBP/CVB/POB/PLB X5EL-AX0/SXD/SAXD POIN-CFP/CGBP/CGBP/CDB/ACA TT-A/C TTA-A/C	Power Supply Current Power Consumption
838 22534	Applicable for, ELECYLINDER	D00H-CB/C0B/C9/P0B/PLB ASEL-C/CS S00H-C/CA/CAL/CGAL SSEL-C/CS S00H-CB/CAL/CGAL C/CG K-F MSEI-0/CS	Insulation Resistance
	Position Controller & Program Controller	SOUNZ-CH/VA/FT MSEL-FO/FO/FO/FO/ ERC2_ERC3_RCP68_ROBONET RSEL_XSEL2-T/TX	Grounding
	First Step Guide Twelfth Edition	ROM-P6AC/P6PC/P6DC EC, REC, CCM, ADTB, RP MCOON-C/GG/LC, MSCON-C, RCON ASEP DSEP DMEC	LC/Backlight
	Thank you for purchasing our product.	MSEP-C/LC Note When updating firmware, please add new information.	Backlight Life
	Make sure to read the Safety Guide and detailed Instruction Manual as well as this First Step Guide to ensure correct use. This Instruction Manual is original.	4. Harrista David Madal Marsharr	Touch Panel Life
	Λ Warning : Read the instruction manual carefully and follow the instruction manual when	4. How to Read Model Number	External Memory
	handling this equipment.	<u>TB-02</u> - <u>SC</u> - <u>SWR</u> - <u>ENG</u>	Data Storage
	You can download it free of change. User registration is required for first time users.		Data Storage
	URL:www.iai-robot.co.jp/data_dl/CAD_MANUAL/ Keep a printout of the introduction manual near the equipment in which this product		Touch Tone
	is installed so that it can be checked at all times, or display it on your computer,	<model number=""></model>	Display Adjustment
	If you need a bound copy of the instruction manual, order it from the nearest sales	TB-02D : With deadman system control of the	Clock Setting
	provided for a fee.	(left side) (Display can be changed to other language)	Communication Standard
	Using or copying all or part of this Instruction Manual without permission is prohibited.	Not specified Stop switch unit is gray. ENG : Screens are displayed in English. SWR : Stop switch unit is red. (Display can be changed to other	Cable Length
l	The company names, names of products and trademarks of each company shown in the sentences are registered trademarks.	<cable type=""> language) SCN : With No Cable (Main body only) CHI : Screens are displayed in Chinese.</cable>	Wall-mounting Hook
F	tequest to Users Purchased TB-02E/TB-02P The teaching pendant TB-02 and the actuator driving power supply unit ADTB should be delivered separately.	C : With ELECYLINDER / Position Controller Cable (Display can be changed to other language)	Time from Power OFF to ON
ŀ	lave them joint together by referring to "5. How to Join Unit" in [Actuator Driving Power Supply Unit for	SC : With Program Controller Cable, Conversion Cable and ELECYLINDER / Position Controller Cable	Air-cooling System
1	eaching Pendant].	Note : It is necessary to provide a special cable (CB-TB1-XJ005) for XSEL-J/JX controller.	Languages
	powerTB oo	Refer to [Actuator Drive Power Supply Unit for Teaching Pendant] for the model code of the teaching pendant equipped	Mass
	supply TB-02 TB-02P	with power supply unit TB-02E/TB-02P.	Secure Dig
		Controlles model - Currented from version - Controlles model - Currented from version	2 Environmental Specifi
	Dreduct Check	ERC2 (Note 1)/ERC3 V1.00 ASEL/PSEL/SSEL V1.00	
	Product Gneck	ACON/DCON/PCON (Note 5) V1.00 TT/TTA V1.00	Ambient Operating Temperatu
T I'	he standard configuration of this product is comprised of the following parts. you find any fault with the product you have received, or any missing parts, contact us or our distributor.	SCON (Servo Press Type) V1.40 MSEL-PC/PG/PCX/PGX V1.00	Ambient Operating Humidity
1	. Parts (The option is excluded)	SCON2 V4.10 XSEL-J/JX V1.00	Ambient Storage Temperature
-	No. Part Name Model Q'ty Reference Main Body (with 5m Refer to "How to Read model Nameplate" Standard cable is fixed on	MCON (Note 2) /MSCON V1.00 XSEL-K/KX/KT/KRT V1.00 RCON (Note 4) V/2.10 XSEL-P/O/PCT/OCT V1.00	······
-	standard cable) "How to read model Number"	RCP6SV1.00XSEL-PX/QXV1.00	Vibration Endurance
_	2 ELECYLINDER / CR TR1 C002 1 When model C and SC coloring	RCM-P6□C V1.50 XSEL-R/S/RX/SX/RXD/SXD V1.00 RACON//RDCON V/1.00 XSEL-R/S/RX/SX/RXD/SXD V1.00	Altitude
-	Position controller cable CB-TB1-2002 In When model S and SC selected When model S and SC selected	ASEP/DSEP/PSEP/MSEP V1.00 XSEL=RAX/SAX/RAXD/SAXD V1.30	Atmosphere
-	4 Conversion Cable CB-SEL-SJS002 1 When model S and SC selected	AMEC/PMEC V1.00 RSEL V2.70	Pollution Level
	5 Touch Pen TCH-TB02 1 Provided with the main body $\phi 4.5 ext{ x 102mm}$	ADTB-PEC V4.40 ROBOPUMP V4.70	Degree of Protection
-	6 Safety Guide M0194 1 7 First Step Guide ME0358 1 This guide		Protective Class against
	. Instruction manuals related to this product.	Supported Models	Electric Shock
ļ	No. Name Manual No.	Supported Medale of Desition Controller Supported Medale of Drogrom Controller	
_	1 ELECYLINDER Instruction Manual ME0355	Supported Models of Position Controller Supported Models of Program Controller	
-	Touch Panel Teaching Pendant TB-02 Applicable for Program Controller Instruction ME0356 Actuator with Integrated ERC2 Controller Instruction Manual <pio sio="" type=""> ME0158/0159</pio>	Hote is only a rot in the rot of high rot in gend attribute on the content for data of an be connected. However, touch-panel teaching pendants can be connected to ERC2 controllers of SE type via a SIO converter	Front
-	Actuator with Integrated ERC3 Controller Instruction Manual ME0297	For details, refer to the instruction manual.	Standard Specification
-	5 PCP6S Field Bus Communication Instruction Manual ME0349 6 ACON-CA/DCON-CA Controller Instruction Manual ME0326	Note 2 Applicable in V1.20 and later for SSCNET III/H and MECHATROLINK- III in MCON-C/CG.	Deadman Switch Spe
_	7 ACON-CB/CGB, DCON-CB/CGB Controller Instruction Manual ME0343	Applicable in V3.00 and later for EtherCAT Motion. Note 3 Applicable in V3.00 and later for EtherCAT Motion in SCON-CB/CGB.	
	9 PCON-CA/CFA Controller Instruction Manual ME0034	Note 4 Applicable in V3.10 and later for SSCNET Ⅲ/H, MECHATROLINK- Ⅲ and EtherCAT Motion in RCON. Note 5 Applicable for PCON-CBP/CGBP from V3.50 and later	19
-	10 PCON-CB/CGB/CFB/CGFP/CGBP Controller Instruction Manual ME0342 11 PCON-CYB/PL B/POB Controller Instruction Manual ME0353		• -
-	12 SCON-CA/CAL/CGAL Controller Instruction Manual ME0243	ELECYLINDER Supported Models	
-	13 SCON-CB/CGB/LC/LCG Controller Instruction Manual ME0340 14 SCON-CB-F/CGB-F/LC-F/LCG-F Controller servo press function Instruction Manual ME0345	Please check our homepage or instruction manual.	
-	15 SCON2-CG Controller Instruction Manual ME0458	URL : www.iai-robot.co.jp/knowledge/support/teaching_version/EC_support/TB02_03_support.pdf	
	10 SCON2-OS-P Controller serve press function instruction manual MEO470 17 ROBONET Instruction Manual ME0208	Supported Models of Cateway Parameter Setting Tool	
F	18 ASEP/PSEP/DSEP Controller Instruction Manual ME0267 19 PMEC/AMEC Controller Instruction Manual ME0245	Controller model Supported from version Controller model Supported from version	15
_	20 MSEP-C/LC Controller Instruction Manual ME0299	MSEP-C V1.00 RCP6S Gateway V1.00	
F	Z1 MCON-C/CG Controller Instruction Manual ME0341 22 MSCON Controller Instruction Manual ME0306	MCON-C/CG (Note 7) V1.00 RCON (Note 7) V2.10 REC V2.70 V2.10 V2.10	
F	23 RCON System Instruction Manual ME0384	Note 6 SSCNET II/H, MECHATROLINK-III and EtherCAT Motion in MCON-C/CG are not applicable.	
ŀ	24 NGLE system Instruction Manual ME0392 25 REC System Instruction Manual ME0394	Note 7 Applicable in V3.10 and later for SSCNET Ⅲ/H, MECHATROLINK- Ⅲ and EtherCAT Motion in RCON-GW/GWG. Note PLC Feature Equipped Types (MSEP-LC. MCON-LC/LCG and RCON-LC/LCG) are not applicable.	
F	26 ASEL/PSEL/SSEL Controller Instruction Manual ME0165/0172/0157 27 MSEL-PC/PG/PCE/PGE/PCX/PGX Controller Instruction Manual ME0336		
Ľ	28 XSEL-P/Q/PCT/QCT Controller Instruction Manual ME0148 28 XSEL-P/Q/PCT/QCT Controller Instruction Manual ME0148		
ŀ	29 XSEL-PX/QX Controller Instruction Manual ME0152 30 XSEL-R/S/RX/SX/RXD/SXD Controller Instruction Manual ME0313		
ļ	31 XSEL-RA/SA/RAX/SAX/RAXD/SAXD Controller Instruction Manual ME0359		
-	32 ASEL2 Controller Instruction Manual ME04/8 33 Tabletop Robot TT/TTA Controller Instruction Manual ME0149/0320		
F	34 ROBOPUMP Instruction Manual ME3827		
L			

Confirming the Specifications

Basic Specification				
Position controller / ELECYLINDER connection	Program controller connection			
24V DC±10% (Sup	plied by controller)			
150mA	or less			
3.6W d	or less			
500V DC /10MΩ or more	e between GND and FG			
- Functional ground (by shield in the connection cable with controller)				
7-inch color TFT WVGA (800×480), 655	36 colors (16 bits)/White LED backlight			
15000	hours			
4-wire resistive type				
1 million touches				
SD/SDHC memory card interface installed (1G to 32G) (Toshiba-made recommended)				
Applicable to have data saved to and read from external Secure Digital card (Position data, parameter, alarm list)				
5 years				
Turned ON/OFF. Volume is adjustable by 3 stages (High/Medium/Low).				
Brightness adjustable for contrast and backlight				
Clock setting available with real time clock	(Backup held with CR2032 button battery)			
Based on RS485	Based on RS232			
115,200bps	9,600bps/19,200bps/38,400bps /57,600bps/115,200bps/230,400bps			
Standard 5m/Max. 10m				
Hook available to use with M8 hex socket head cap screw				
2 sec o	r more			
Natural a	ir-cooling			
Japanese/Eng	glish/Chinese			
TB-02: Approx. 470g (Main body) + Approx. 330g (cable 5m) TB-02D: Approx. 600g (Main body) + Approx. 330g (cable 5m)				

cure Digital memory card is a registered trademark for SD-3C, LLC and SDA.

ifica	tions					
	Environmental Specifications					
ture	0 to 40°C					
	5%RH to 85%RH (Should be no-condensing or freezing)					
e	-20 to 70°C					
	5%RH to 85%RH (Should be no-condensing or freezing)					
	Vibration 10 - 57Hz/Amplitude: 0.035mm (continuous), 0.075mm (intermittent) Vibration 57 - 150Hz/Acceleration: 4.9m/s ² (continuous), 9.8m/s ² (continuous) X/Y/Z direction Sweep time: 10 min. Sweep repetition: 10 times					
	1000 meters or less above the sea level					
	Environment without corrosive and combustible gas. Avoid using the equipment where there is much dust and oil mist/ cutting fluid is sprinkled.					
	П					
	IP20					
	Ш					

External Dimensions

Side

ification ch Specification



Standard Specification (without Deadman Switch)



Deadman Switch Specification







(Note) For other wiring except connection with Touch Panel Teaching Pendant TB-02, refer to the first step guide or instruction manual of each controller.



Switch OFF The hand is off the switch, or the switch is pressed with a very small force. Switch ON The switch is pressed with an appropriate force. Switch OFF The switch is pressed with a strong force.

When the switch is ON, the servo can be turned ON. When the switch is OFF, the drive source is cut off and the servo remains OFF.

Even when the switch is OFF, operation is still possible in modes where the servo need not be ON (such as in the edit mode)



Explains the position data input and trial operation according to the real position data editing screen in

Explains the positioning action by I/O control under the "PIO pattern:0" condition in interactive mode as the user operates the equipment according to instructions.

Sets the data necessary for a desired action from the sample program and performs trial operation in order

Displays the actuator status, I/O signal status, maintenance information and production information.

Sets the position, velocity, acceleration, deceleration, etc. to operate actuators. It is available to manual

Adjusts parameters when adjusting the system and using the attendant functions.

Reads and saves the position data, parameters and alarm list. Updates the TB-02 software.

Displays the real operating status of actuator with waveforms. It is possible to record data.

Performs manual operation and I/O test by specifying jog, inching and numerical values.

Displays an alarm and the time of its occurrence.

.....

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Shows the software version, network information, production information, maintenance information and

Displays the alarm contents and remedial measure when an alarm occurs.

Selects an axis to be displayed when the controller can be connected with two or more axes.

Prohibits/permits PIO operation and validates/invalidates safety velocity.

Conduct settings for display language, Touch tone, DimDispTime, Data input warning, Disp Axis Name, Ripple compensation, password, display, time and Startup screen setting.

Conduct parameter initialization and change axis No., load cell calibration, load cell inactivation, I/O customize, encoder cable length setting.

Displays the maintenance parts information.

It is possible to set the movement between positions, timer and repeat of specified times. This screen is used for manual continuous operation

Sets for performing the pulse train control.

Returns to the preceding screen

: Returns to the "Menu 1" screen.

Displays the "Glossary" screen.

Stop Status Icon (*1) [Refer to next column]

Glossary

STOP

(III)

Axis No. 00

: Displays the "Monitor" screen

Displays the "Change Axis" screen.

(Note)For details of operation, refer to the screen display or instruction manual

÷		Trou	bleshooti	ing	Glos	sar y 📶		Axis No.
larn	displa	A	larm list	Check mo	del num.	Inquiry		
larm	list							
uch	the ala	rm No.	to check the	alarm des	cription and	perform	troub	leshooting.
No.	Group			Name		Address	Code	Time (bh:mm:ss)
0	Other	PowerUP I	No Error			****	FFF	;;
1	D	Centrelle	er encoder allar	n		****	ØEE	0:19:14
2	D	Centrelle	r encoder allar	n		****	ØEE	0:19:00
3	D	Centrelle	er encoder allar	n		****	ØEE	0:01:51
4	Other	PowerUP I	to Error			****	FFF	:
5	D	Centrelle	er encoder alar	n		8898	ØEE	0:03:39
6	D	Centrelle	ar encoder alar	n		****	ØEE	0:02:08
7	Other	PowerLP I	io Error			****	FFF	
	1 P	r pg	↓Nx pg			Save		Clear

Operation Menu for ELECYLINDER (EC)



- Monitor
- Displays the actuator status, I/O signal status, maintenance information and production information.
- Simple Data Setting Setting can be established for position, acceleration (A), velocity (V), deceleration (D) and pressing force to operate an actuator.

Display of the current position and cycle time, and the changing history of AVD settings can be displayed. Manual operation is also available.

- Setting of ROBOPUMP Adsorption, desorption, monitor display and setting of ROBOPUMP should be conducted.
- Parameter edit
- Conduct settings such as to adjust operation range or home position, or to change the direction of home-return operation.
- SD memory card
- Reads and saves the position data, parameters and alarm list. Updates the TB-02 software. Test run
- Performs manual operation and I/O test by specifying jog, inching and numerical values.
- Alarm list
- Displays an alarm and the time of its occurrence.
- Information Shows the software version, production information, maintenance information and connectable model
- information.
- Troubleshooting
- Displays the alarm contents and remedial measure when an alarm occurs.
- Change operating axis
- An axis subject to display can be selected when multiple axes are connected. • TP op. mode
- Prohibits/permits PIO operation and validates/invalidates safety velocity.
- Env. set.
- Conduct settings for display language, Touch tone, DimDispTime, Data input warning, Disp Axis Name, Ripple compensation, password, display, time and Startup screen setting. Controller reset
- Restarts the controller
- Other setting
- Initializing of parameters, changing axis numbers and tuning operation volume can be conducted. Maintenance parts list
- Displays the maintenance parts information.
- Easy programming

It is a screen to set up a manual continuous operation, and movement to the forward end and backward end and setting of timer and repeat setting with number indication are available. (Note) For details of operation, refer to the screen display or instruction manual.

 \leftarrow : Returns to the preceding screen. ssar y 🕕 📶 ty □Push Cycle time 1.969 s : Returns to the "Menu 1" screen. Push 1. 603 s 30 vole time V:Vel Glossary Displays the "Glossary" screen. STOP : Stop Status Icon (*1) : Displays the "Monitor" screen. EEN Cur. pos. 0. 00 mm 0.00 mm 150.00 mm Displays the "Change Axis" screen. Axis No. 00 Unit Change

*1 Stop Status Icon: The icon blinks in the following conditions.



Operation Menu for Position Controller (SEP System) SEP Menu screen

Screen at SEP System Controller Startup



Monitor

- Current position, speed, current and system status I/O of the controller is displayed. Information
 - Information such as operation pattern and software version is displayed.
- Alarm list List of alarms, duration of occurrence and occurred time is displayed.
- Change ax
- Axes to be displayed for a controller available for multiple axes connection can be selected.
- Position setting Settings related to position such as position, speed, acceleration, push power and push band in order to drive an actuator can be conducted. Also, JOG / Inching movement can be performed.
- Initial setting Setting of operation patterns and operation modes, parameter edit, operation test for I/O and axes and
- environment setting can be conducted.
- Data backup

Reading out and saving of data such as position data, parameters and alarm lists can be conducted.

Operation Menu for Position Controller (MEC System)



- Initial setting
- Setting for the operation patterns (2-point stop, 3-point stop) can be conducted.
- Position setting Setting of such as position, pressing force and pressing band, and manual axis operation can be conducted.
- Test run
- Operation test for axis movement can be conducted.
- (i) (Information)
- Information such as operation patterns, software version and manufacturing information is displayed. • 🚮 (Maintenance)
- Parameter edit, I/O test, alarm list display, data backup, environment setting and axis operation change can be conducted.
- 6 (Monitor)
- Current position, speed, current and system status I/O of the controller is displayed.



- Network setting an be conducted.
- Monitor
- Data monitor, diagnosis information and alarm list are displayed.
- Storage of the gateway setting data to the Secure Digital memory card and reading out from the Secure Digital memory card are to be conducted.



Axis No. 00

Edit	
Play	
Monitor	
Controller	
Edit Play	lonitor

Edit

- status and performs manual operation (teaching).
- Play
- Monitor status, system status, etc.
- Controller
- File Environment Set
- Update
- Updates the TB-02 software.



(Note)



- [Cautions]
- updated.

⚠े Warning:	As keys do not attempt program, et



enu for Program Controlle	r (SEL System)
---------------------------	----------------

roller starts	_		
OLLER			
ch Pendant] 1.10 1.00			
ection			
-		Menu 2 screen	
		Henu2	
File		Teaching update	
Environment Set			
Next			Prev.
		Update	->

Edits position data, programs, symbols, parameters and coordinate system data. Displays the actuator

Performs program operation and checks the task status.

Displays I/O port, global flag, global variable, error list, version information, maintenance information, axis

Sets and outputs operation commands for "Flash ROM Writing", "Software Reset", "Error Reset", "Memory Clear", "Re-connection", "Baud Rate Change", "Request Power Recovery", "Request Release Pause", "Absolute Reset". "Safety Velocity". "Multi Task". etc.

Reads and saves position data, programs, parameters, symbols, error list and global data.

Sets the language, touch tone, turn-off time, display and time.

: Returns to the preceding screen.

The displayed screens and executable functions are different between the controller models. For details, refer to the instruction manual.

Screenshot

It is possible to save the image on the current screen (screenshot) into SD memory card

When you want to capture a screenshot, press the lower right portion on the screen for about 2 seconds longer than usual on condition that SD memory card is inserted.

After a short sound is heard, saving the screenshot starts. (If the touch tone is set to "OFF", the sound is not heard.) When saving is completed, the save file name is displayed for 3 seconds on the screen.

> File name : IMG YYMMDDHHMMSS.bmp Example When the save processing starts at 12:34:56 on Mar. 8, 2016, the file name is "IMG 160308123456.bmp".

> > Insert SD memory card beforehand.

> > Press this portion longer than usual.

1. The saving process takes approximately 10 seconds at the maximum.

2. During the saving process, the monitor display (such as the current position) on the screen does not get

3. There are some screens that you cannot get screenshots.

not work on the screen during saving process, emergency stop will not work. Do to use this feature when an actuator is operated (continuous movement, simple tc.) from the teaching.

Actuator Driving Power Supply Unit for Teaching Pendant

. Basic S	Specification				
Item			Specification		
Rated Input Voltage			Single-Phase AC100 to 230V ±10%		
Input Current			1.4Atyp. (AC100V), 0.6Atyp. (AC230V)		
Frequenc	y Range		50/60Hz±5%		
Power Ca	apacity		141VA (AC100V), 145VA (AC230V)		
Output Vo	oltage		DC24V ±10%		
	ELE CYLINDER	Standard, High-Stiffness, Dustproof and splashproof	When Power Saving Setting Invalid: Rating 3.5A, Max. 4.2A When Power Saving Setting Valid: Rating 2.2A, Max. 4.2A		
Load		Slim and Small	Max. 2.0A		
ounon	ROBO CYLINDER	20P, 20SP, 28P, 35P, 42P, 42SP, 56P	When High Output Setting Invalid: Max. 2.2A When High Output Setting Valid: Rating 3.5A, Max. 4.2A		
		56SP, 60P, 86P	Max. 6.0A		
Output Ca	apacity (ELEC	YLINDER)	When Power Saving Disabled: Rated 84W, Max. 98.4W When Power Saving Enabled: Rated 52.8W		
Heat Radiation 20P, 20SP, 20SP, 28P, 35P, 42P, 42SP, 56P		20P, 20SP, 28P, 35P, 42P, 42SP, 56P	RCP2, RCP3 : 5W RCP4, RCP5, RCP6 : 8W		
、	,	56SP, 60P, 86P	19.2W		
Ambient	Operating Terr	perature	0 to 40°C (Should be no-condensing or freezing)		
Ambient (Operating Hun	nidity	5%RH to 85%RH (Should be no-condensing or freezing)		
Ambient	Storage Temp	erature	-20 to 70°C		
Ambient	Storage Humio	dity	5%RH to 85%RH (Should be no-condensing or freezing)		
Atmosphe	ere		There should be no corrosive gas around, especially be mindful of dust		
Altitude			1000 meters or less above the sea level		
Vibration Endurance			Vibration 10 - 57Hz/Amplitude: 0.075mm Vibration 57 - 150Hz/Acceleration: 9.8m/s ² X/Y/Z directionSweep time: 10 min. Sweep repetition: 10 times		
Drop in Package			Dropping Height 800mm, 1 corner + 3 edges + 6 surfaces		
Overvolta	ige Category		I		
Pollution Level			2		
Protection	n Class for Ele	ectric Shock	П		
Degree o	f Protection		IP30		
Mass			ADTB-EC : Approx. 740g / ADTB-PEC : Approx. 825g		
Air-coolin	g System		TB-02E : Natural cooling / TB-02P : Forced air cooling with internal fan		

2. How to read the model No.

1) Model Code for Actuator Driving Power Supply Unit (ADTB) Individually

ADTB-<u>EC-EC-5-1-BKT</u>



TB-<u>02E</u>-<u>C</u>-<u>SWR</u>-<u>1</u>-<u>ENG</u>



- <Type> _____ 02E : For ELECYLINDER (CB-ADTB-PW050-RB, CB-TB1-C002 Enclosed) 02P : In common for ELECYLINDER / ROBOCYLINDER (CB-ADTB-PW050-RB, CB-TB1-C002 Enclosed)
- 3) Model Code for Enclosed Cables Individually
- 100V AC Power Supply Cable: KWD-UJ-2MBS (Cable length should be 2mm)
 200V AC Power Supply Cable: CB-APMEC-PW020-TM (Cable length should be 2mm)



4. External Dimensions





5. How to Join Unit (1) Attach the attachment bracket on the back of a teaching pendant.

(2) While pressing the slide lock release (broken line areas) on the driving power supply unit, slide the slide locks (solid line areas) outside to make them open.



(3) Insert the slots (broken line areas) formed between the teaching pendant and the attachment bracket to the linkage guides (solid line areas) on the actuator driving power supply unit from the right side.



(4) Insert the teaching pendant along the linkage guides on the actuator driving power supply unit till the teaching pendant reaches the area marked with the broken line.







6. Connection





(5) Slide the slide locks till it gets locked in order to lock the teaching pendant.

7. Applicable Actuators

There are EC Type (ADTB-EC) that capable of operation of ELECYLINDER only and PEC Type (ADTB-PEC) that is capable of operation of ELECYLINDER and pulse motor mounted ROBOCYLINDER

EC Type ····· Trial run of ELECYLINDER (24V pulse motor type) is capable.

PEC Type ··· Trial run of ROBOCYLINDER (pulse motor type: RCP2 Series and later) and ELECYLINDER (24V pulse motor type).

8. Trial operation (1) ELECYLINDER operation

When having a trial run of ELECYLINDER, as an actuator is operated by the controller built in ELECYLINDER, ADTB is to be used only for power supply to ELECYLINDER.



Supply power to ELECYLINDER and ELECYLINDER can operate in normal condition.

(2) ROBOCYLINDER operation When having a trial run on ROBOCYLINDER, ADTB can be a simple controller. Operation such as jog operation in low velocity without using parameters and operation with parameters applicable for a position controller installed separately read from a Secure Digital card to ADTB is capable.



Coordinate Confirmation **Operation Mode**

Operation should be made with parameters for ADTB-PEC read in. Editing positions and position data operation are capable.

[About Parameter File for ADTB-PEC]

- The parameter file for ADTB-PEC is necessary in order to switch over to the coordinate
- confirmation operation mode. A parameter file for ADTB-PEC cannot be created by a user.

If a parameter file is required, confirm the model code of an actuator and the serial number described on the model code nameplate sticker attached on the side of the main unit, and request to a sales person in charge.

Treatment in an Emergency

For SEP System / MEC System Controllers

If an alarm occurs, the alarm screen appears. In alarms, there are those generated in a controller and those generated in a touch panel teaching. In response to the alarm code occurred, check in the instruction manual of the controller or instruction manual of the touch panel teaching.

Alarm		Axis No. 00		
Alarm : A.B disconnect Alarm code : 0E8		Error No. (HEX)	Reference	
Detail code Address	: **** : ****		000 to 0FF	Refer to Instruction Manual of Controller
Time(yy/mm/dd) : 16 / 02 / 27 17 : 13 : 57		: 13 : 57	100 to 3FF	Refer to Instruction Manual of Touch Panel Teaching
Back	Alarm reset	Inquiry	-	

For ELECYLINDER, CON System / SEL System Controllers

If an alarm occurs, the troubleshooting screen appears. Touch [How to deal] to confirm the cause, touch [Count.m.] to confirm the countermeasures, conduct the measures and touch [Alarm reset].

Closery Closery	C Troubleshooting Classer	← @ Troubleshooting Clossery
Norm display Alarm Tist Dieck model num, Innuiry	Alarm display Alarm liat Dieck model num. Inquiry	Atom display Alarm List Dieck model num. Inquiry
larn descript.	Troubleshooting 1 [Dause Classification] 3/2 (899:Water/cable Discrimination Error Detection)	Troublesheeting 1 [Cause Classification] 1/2 (#99:Water/cable Discrimination Error Datection)
and	Following items could be the cause, Flesse take a measure corresponding to each item.	Following items could be the cause. Please take a measure corresponding to each ite
Alars code 899 Alars level Power-on again (Cold start)	(1) The power was terred on with the stop switch pressed, (Detail Code : 6064)	(1) The power was turned on with the stop switch pressod, (Detail Code : 8000)
Descr. The power supply was turned on with the step switch of the teaching bew pressed, and motor was not detected. Following are the possible reasons:	② Wisnatch between the connected actuator and the parameter, (Detail Code : BOOT)	② Wiseatch between the connected actuator and the parameter, (Detail Code : 8081)
 A mismic between the corrected actuator and the parameters transferred to ADB accuracy A wrong or defective connecting cable was detected, 	With persenters for high thrust motors (SBSP, 68P, 86P) set to ADEL joint oblice are not connected. (Detail Code: 4962)	It is baraseters for high thrust motors (S65P, 68P, 68P) act to AUE, paint cables are not connected. (Detail Code : 8062)
Detail code: 0004 Adre: **** Time(yy/mm/dd hh:mn:so)//::		
line to deal diam raret	Alarn reset See other	Alarn reset See other



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